Real-time Measurements of the Particle Geometric Surface Area by the Weighted-sum Method on a University Campus

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ABSTRACT

This study conducted field measurements of the particle geometric surface area (GSA) and number concentrations on a university campus via two real-time approaches: applying the weighted-sum (WS) method and using a Scanning Mobility Particle Sizer (SMPS). The measurements were conducted on 4 subjects: laser printing, 3D printing, machining (waterjet cutting, sanding, and welding), and environmental aerosols. The highest emissions were found with 3D printing and welding; these concentrations were measured in the printer’s enclosure and when the local exhaust ventilation was on, respectively. In general, the two methods agreed well with each other, with an overall Pearson correlation coefficient of 0.85, although the concentrations constantly fluctuated over a wide range, from 20 to 4 × 10⁴ μm² cm⁻³. Since the GSA concentrations reported in this study are the first measurements for some scenarios, our results can serve as a reference for further research as well as for individuals in the vicinity of these emissions.

Keywords: Geometric surface area; Real-time; Weighted sum; Occupational exposure; 3D printing emission.

INTRODUCTION

Since recent toxicological studies showed that the surface area of nanoparticles has better correlation with the adverse health effect than their mass (Oberdörster, 2000; LeBouf et al., 2011; Schmid and Steoger, 2016), more surface area measurements were conducted and discussion was aroused about some kind of surface area should be introduced as an additional metric (Ramachandran et al., 2005; Balaout et al., 2016) to characterize the nanoparticle exposure and health effects. More specifically, Schmid and Steoger (2016) concluded that for nonporous spherical particles the geometric surface area (GSA) can be “used as biologically most relevant dose metric,” where the GSA is defined as the envelope surface area of particles. The well-known Scanning Mobility Particle Sizer (SMPS) offers quasi-real-time size-resolved particle size distribution in minutes. Mobility-based surface area can be calculated based on the integrated distribution. Note that for spherical particles, the surface area is equal to the GSA. There are other techniques to measure aerosol parameters close to the GSA in different time resolutions. The offline BET method (Brunauer et al., 1938) measures the accumulative specific surface area, used as a metric in many toxicology studies (Bau et al., 2011; LeBouf et al., 2011). Schmid and Steoger (2016) pointed out that for porous and arbitrarily shaped particles (except fibers), the BET surface area is expected to be the biologically more effective dose metric than the GSA. However, in contrast to the GSA, there is currently no real-time BET method due to its high detection limit that leads to tremendous amounts of sampling time when the majority of the aerosol are submicron particles. Thus, for nonporous spherical particles, the GSA can be used as biologically most relevant dose metric. Electron microscopy, another offline method, provides visualization and quantitative analysis of the 2D projection of sampled particles. Bau et al. (2010) had developed a TEM-based method as an alternative to the BET method. However, researchers are still struggling to reduce the time for routine analysis of TEM images and the uncertainty caused by human subjectivity and measurement reproducibility (Bourrou et al., 2018). The epipheniometer (EPI; Gäggeler et al., 1989) is the first device designed specifically to monitor the active surface area of aerosols of any kind via the calculation of the attachment rate of labeling material to the aerosol. Gini et al. (2013) later developed a six-stage cascade epipheniometer (CEPI) to measure the distribution of aerosol active surface area in real time. However, the inclusion of a radioactive source (227Ac) as the labeling material makes the EPI inappropriate for routine field use.

Diffusion chargers (DC) (e.g., the Electrical Aerosol Detector [EAD] Model 3070A; TSI Inc.) can also measure the active surface area in real time. DC shares a common operation principle with the EPI. However, the use of the
electrical ions as the labeling material makes it very popular in field measurements. Due to the need of in situ exposure measurements, many DCs were modified (Fissan et al., 2007; Marra et al., 2010; Fierz et al., 2011, 2013) and calibrated based on ICRP lung deposition curve (ICRP, 1994) in order to measure the particle lung-deposited surface area (LDSA) concentration, which is expected to be great in aerosol exposure measurement. Because of the portability and real-time capability, many environmental measurements for exposure monitoring were using DC (Mokhtar et al., 2013; Todea et al., 2015; Geiss et al., 2016). Iavicoli (2018) applied several DC to conduct personal exposure sampling, which will be very difficult for other bulkier benchtop instruments. Kuuluvainen et al. (2018) even installed DC into a multirotor drone to study the vertical profile of the aerosol LDSA concentration of a street canyon.

However, the GSA on which many toxicological data are based is still more relevant to toxicity than active or lung-deposited surface area. Furthermore, the active surface area is only a portion of the GSA by the definition and measurements (Pandis et al., 1991; Jung and Kittelson, 2005). Ku (2010) found that the deviation of the DC-based surface area from the GSA was up to 94% from 100 to 900 nm. Some progress was made on the manipulation of the DC response (Fierz et al., 2008; Li et al., 2009; Marra et al., 2010; Cao et al., 2015; Fierz et al., 2011) towards the GSA measurements (Wei, 2007; Cao et al., 2017). Based on the previous studies, Cao and Pui (2018) developed a weighted-sum (WS) method coupled with DC with a potential resolution of 1 s, where the instrument response correlates well with the GSA of spherical particles with a much wider working range compared with previous studies. Based on the WS method, we developed more methods and prototypes with 1-s resolution to measure the GSA and other parameters for particles in different shapes (Su et al., 2019a, b).

Since the method has only been established recently, more field measurements are needed to explore the possibility of the WS method on more scenarios. Note that although many studies on field measurements were using SMPS that can offer the GSA concentration, the data were not always expressed in the form of the GSA since they were using SMPS as a comparison to other surface areas (e.g., LDSA) other than the GSA. Thus, a GSA concentration reference that individuals and researchers can refer to is missing. The current study applies the WS method (Cao and Pui, 2018) along with SMPS and conducts several field measurements where emission concerns were raised on a university campus. The events of measurements include laser printing, 3D printing, machining (waterjet cutting, sanding, and welding), and outdoor air quality. The emission profile could add to the database of GSA measurements and serve as a reference for future studies.

**METHODOLOGY**

The current investigation involved field samplings of aerosol geometric surface area concentrations on the University of Minnesota campus. The data can help explore the possibility of the weighted-sum method (Cao and Pui, 2018) for various environments and provide a reference on environmental GSA concentrations.

The WS method and SMPS, which are both targeted at submicron particles, were sampling by parallel. SMPS consists of a $^{210}$Po neutralizer (TSI Inc.), a Differential Mobility Analyzer (DMA; Model 3081; TSI Inc.), and a condensation particle counter (CPC; Model 3776; TSI Inc.) and delivers the aerosol size distribution (up to 64 particle size bins) in minutes. Both particle number (PN) and GSA concentrations/distributions can be delivered by SMPS. Note that all the PN concentrations mentioned in this study were measured by SMPS. We used 0.3 L min$^{-1}$ as the aerosol flow rate (CPC) and 3 L min$^{-1}$ as the sheath flow rate of DMA. One cycle of SMPS scan is 60 s, 50 s of sampling and 10 s of retrace.

The WS method was designed to monitor aerosol GSA concentrations in real time by correlating the instrument response with the integral of aerosol GSA concentrations. The method applies a novel mathematical algorithm on top of the unipolar diffusion charging, where two independent signals within several seconds are combined in a weighted-sum fashion to correlate with aerosol GSA concentrations. The WS method used the Nanoparticle Surface Area Monitor (NSAM; Model 3550, discontinued as of March 31$^{st}$, 2018; TSI Inc., Shoreview, MN; Fissan et al., 2007) as the basic instrument. The aerosol first got charged by the positive ions, excess ions were then removed in the trap (an electrostatic precipitator), and finally, the electrical current produced by the charges on the particles was measured by the electrometer (Fig. 1). Several researchers found that by altering the voltage ($V$) of the trap, the instrument sensitivity (the ratio of the total current to the total PN concentration) for monodisperse, spherical particles can be manipulated and became proportional to the GSA of a single particle (Wei, 2007; Li et al., 2009), which is the sufficient condition for a direct reading monitor to measure the integrated GSA for the aerosol (Fissan et al., 2007; Wei, 2007). However, the working range is limited, e.g., 20–100 nm in Wei (2007). Cao and Pui (2018) found that when combining two independent sensitivities under two carefully chosen voltages for the same aerosol in a weighted-sum fashion (Eq. (1)), the proportionality between the GSA and instrument response can be achieved (Eq. (2)) in a much wider range, 20–300 nm:

$$S_{WS} (d, V_1, V_{2c}) = S(d, V_1) + cS(d, V_2)$$  \hspace{1cm} (1)

where $S(d, V_1)$ is the sensitivity at 20 V, $S(d, V_2)$ is the one at 2400 V, and $c$ is the weighting factor (a constant) that can be determined by the instrument calibration, and

$$kS_{WS} (d, V_1, V_{2c}) = nd$$  \hspace{1cm} (2)

where $k$ is a constant that can be easily determined when $S_{WS}$ is known.

As described in Eqs. (1) and (2), the sensitivity was rigorously tested with monodisperse, nearly spherical particles (KCl in Cao and Pui, 2018; PSL and gold in Cao et al., 2017) size by size from 20 nm up to 487 nm during the calibration. To obtain two independent instrument responses (electrical...
currents) for the combination, the voltages of the trap were switching back and forth in a stepwise pattern between 20 V and 2400 V, which is controlled by Labview 2014 (National Instruments). In every 60 s, the voltage stayed at 20 V for the first 30 s and 2400 V for the second 30 s. When switching the voltage from 20 V to 2400 V, we observed a 3-s delay for the current; when switching from 2400 V to 20 V, the delay time was about 25 s. Thus, for usable data, we only took data from time $t - 5$ to $t$ and $t + 5$ to $t + 10$ if we define the time of switching from 20 V to 2400 V as time $t$. We averaged 6 data points for 20 V from time $t - 5$ to $t$ and 6 data points for 2400 V from $t + 5$ to $t + 10$ and obtained the standard deviations ($\sigma_{20}$ and $\sigma_{2400}$). Two averaged values were combined according to Eq. (6) in Cao and Pui (2018) and the standard deviation for the combined data is $\sqrt{\sigma_{20}^2 + c^2 \sigma_{2400}^2}$ according to the propagation of uncertainty rules. Note that we assumed the aerosol was stable within 16 s. If the averaged value is not needed, the assumed stable time is only 6 s.

Although the algorithm itself has no limitation on the time resolution, the hardware was not optimal and the potential of the algorithm was not maximized in the current measurements. Fortunately, in our recent studies, Su et al. (2019a) applied two parallel DC for the algorithm, one with a high voltage and another with a low voltage, and maximized the resolution to 1 s. Furthermore, Su et al. (2019b) had extended the WS method to both the GSA and mass measurement for lab-generated nano-agglomerates and aggregates.

The field measurements include several representative indoor/outdoor emission events and the detail was listed as follows:

**Laser Printing in the Student Computer Lab**

The particle emission of a laser printer was measured in the student computer lab on an ordinary Tuesday afternoon, March 14th, 2017. Fig. 2 shows the working principle of laser printing. Laser printing is an electrostatic digital printing process. First, the photoreceptor drum is positively charged by the corona wire. As the drum revolves, a laser beam
The remaining positively charged area of the drum is coated with the negatively charged toner and rolls over a sheet of paper. Finally, the paper with the attached toner passes through the fuser, a pair of heated rollers (137–205°C in He et al., 2010). As the paper passes through the fuser, the loose toner powder and the paper melt together and the paper is printed. Morawska et al. (2009) indicated that the fusing could be the major source for particle emission.

The printer, a color laser printer (HP LaserJet M651), was located against the wall of the room near the room entrance. The room is a regular computer lab containing a total of 30 computers on the tables. The aerosol instruments located 10 cm away from the outlet of the exhaust fan of the printer to make sure the emission is high enough and distinguishable from the background. During the 1-h continuous sampling, 4 print jobs happened and were fully covered by the sampling. The print jobs include the printing of black plain texts (~5% toner coverage), text and pictures in color (~10% toner coverage), pictures in color (~40% toner coverage), and pictures in red (~20% toner coverage) chronologically. More detail of the prints can be found in Table 1.

3D Printing in the Student Workshop

The 3D printer we aim to measure, Dimension 1200es SST from Stratasys Inc., is a fused deposition modeling (FDM) printer with dual extruders. The printer comes with an enclosure and an internal air-circulation system (4 chamber fans, 1104 L min⁻¹) with HEPA filters, which intends to maintain a uniform temperature to reduce filament warping. The measurement was carried out in a room that was 4.3 m long and 3.7 m wide (Fig. 3). The max airflow for the room is approximately 28,317 L min⁻¹ with 6 air changes per h. The Dimension 3D printer was against the wall and the aerosol instruments were next to the 3D printer in the middle of the room. Two other 3D printers, both Fusion 3 F410, were in the room as well. The one next to Dimension was out of service and the one in the upper left corner was printing during the whole field measurement. For the 3-h continuous sampling, two identical wrenches were printed with dual extruders during the measurement, one loaded with acrylonitrile butadiene styrene (ABS) filament for the main-body print and another with support material SR 20, which is mainly acrylic copolymer. A simple schematic diagram of the working principle of 3D printing is shown in Fig. 4. At the beginning of the printing, the enclosure and materials in the extruder nozzle were preheated to approximately 75°C and 300°C, respectively. The materials were then extruded layer by layer on the building plate, where the two extruders switched back and forth depending on how the 3D model was sliced, namely, translated into individual layers. When the print was finished, the support material was removed manually from the main body. The concentrations were measured outside and inside the enclosure for the 1st and the 2nd prints, respectively. The sampling inlet for the 1st print located about 20 cm away from the enclosure door, while the one for the 2nd print was inside the enclosure close to the door.

Machining in the Machine Shop

The measurement was planned in the machine shop in the Mechanical Engineering Building from 11:00 to 16:00. Multiple events were measured including waterjet cutting (Mach 2 2020c; Flow International Corporation), belt grinding (Model 760; Burr King), and welding. Waterjet is capable of cutting a wide variety of materials using a very high-pressure jet of water, or a mixture of water and an abrasive substance. Here, we used the high-performance garnet abrasives (80 HPA; Barton International) for cutting a metal sheet. Belt grinding is an abrasive machining process, which runs an abrasive-coated belt over the surface of the part to be processed. A metal part was ground during the measurement. Welding is a process that joins materials, usually metals, by using high heat to melt and fuse the parts. Two pieces of metal were welded during the measurement. Note that in the middle of sanding and the whole process of welding, the local exhaust ventilation (LEV) was on so that emission was quickly reduced to protect the operators.
Table 1. Detailed information on four different printing scenarios.

<table>
<thead>
<tr>
<th>Duration (min)</th>
<th>Toner coverage</th>
<th>Highest GSA concentration (WS; μm² cm⁻³)</th>
<th>GMD</th>
<th>øg</th>
</tr>
</thead>
<tbody>
<tr>
<td>Black plain texts</td>
<td>A</td>
<td>3.5</td>
<td>~5%</td>
<td>58.9 ± 3.6</td>
</tr>
<tr>
<td>Texts and pictures in color</td>
<td>B</td>
<td>1.8</td>
<td>~10%</td>
<td>112.3 ± 14.9</td>
</tr>
<tr>
<td>Pictures in color</td>
<td>C</td>
<td>7.0</td>
<td>~40%</td>
<td>381.8 ± 51.3</td>
</tr>
<tr>
<td>Pictures in red</td>
<td>D</td>
<td>5.0</td>
<td>~20%</td>
<td>118.5 ± 26.2</td>
</tr>
</tbody>
</table>

Fig. 3. Room layout for the measurement.

RESULTS AND DISCUSSION

Following the order in Section 2, this section shows the results of the GSA concentration for each event, where data from both WS and SMPS were included and compared. The overall linear comparison of the GSA concentrations between SMPS and WS is presented in Fig. 5, where the overall Pearson correlation coefficient is 0.85 and the specific coefficient for each event will be introduced in each subsection. Many other figures (Figs. 6(a), 7(a), 7(b), 8, and 9) are displayed in a concentration-time manner, where the y-axis corresponding to the concentration is a logarithmic scale. Error bars (standard
deviation defined in Section 2) for the data in 1 min are shown in gray for the WS measurements, while SMPS obtained 1 data point per min and had no error bars. In general, the results obtained by both methods are consistent in the trend as well as the GSA concentrations, whether at high concentrations in emission episodes or low concentrations for the background in the range of $30$ to $4 \times 10^4 \, \mu m^2 \, cm^{-3}$. Note that when the concentration changed rapidly relative to the sampling time of WS (16 s), e.g., in welding, several large uncertainties can be found in nearly all the figures except the

**Fig. 4.** The working principle of FDM 3D printer.

**Fig. 5.** The overall linear comparison of the GSA concentrations between SMSP and WS.
outdoor sampling: the situation of SMPS is even worse because of its much longer sampling time (60 s). In those cases, the scan from SMPS may not accurately represent the aerosol at the time.

**Laser Printing**

The measurement of laser printing in the student computer lab lasted about 1 h. The PN and GSA concentrations of printing of black plain texts, texts and pictures in color, pictures in color, and pictures in red are shown in Fig. 6(a) and their whole print processes from beginning to end are highlighted in shades as A, B, C, and D, respectively. The printing detail was summarized in Table 1 including the event duration, toner coverage, peak concentration, geometric mean diameter (GMD), and geometric standard deviation of the distribution (σg). Note that the GMD is equal to the count median diameter (CMD) in lognormal distributions (Hinds, 1999). Therefore, the CMD reported in other studies can be directly compared with our results.

The background GSA concentration was between 30 and 50 μm² cm⁻³; the concentration peaks for all the print jobs were between 50 and 400 μm² cm⁻³. Note that the background PN concentration (> 6,000 # cm⁻³) is about 7 times higher than that of the clean lab mentioned in Cao and Pui (2018), although the GSA concentrations in both measurements were close at around 40 μm² cm⁻³. We observed huge amounts of nanoparticles at 30 nm in the background (the background in Fig. 6(b)), which contribute a lot to the PN but little to the GSA concentration. In the linear comparison of the GSA concentrations between SMPS and WS (+ in Fig. 5), there was a significant positive correlation with a Pearson correlation coefficient of 0.87 even when the concentrations varied with a span of an order of magnitude.

Many other studies have also monitored the PN and GSA concentrations for laser printing (He et al., 2007; Schripp et al., 2008; Morawska et al., 2009; He et al., 2010; McGarry et al., 2011; Wang et al., 2012). The PN (1.3 × 10⁶ # cm⁻³) and GSA concentrations (6,500 μm² cm⁻³) shown in Fig. 1 in Mokhtar et al. (2013) are more than one magnitude higher than the highest concentration in C, which is 1.3 × 10⁴ # cm⁻³ for the PN concentration and 382 μm² cm⁻³ for the GSA concentration. It is reasonable that the concentration in Mokhtar et al. (2013) is much higher than ours since their measurements were performed in a 1-m³ environmental chamber, where concentrations can easily accumulate, while our field measurements were conducted in the open space, where the emission was quickly diluted by the background. McGarry et al. (2011) measured the particle emission of 107 laser printers in the open-plan offices. The median of peak concentration for all printing events for a high emitter, which is 2.2 × 10⁴ # cm⁻³ (Fig. 2 in McGarry et al., 2011), was comparable to the PN concentration in C. In addition, Morawska et al. (2009) reported an average CMD of 63.5 nm (during the first 2 min of printing) and 28.5 nm (during the middle 2 min of printing) for the submicrometer emission of Printer H with various toner coverage of 0%, 5%, and 50%. The GMD (= CMD) in our measurement was between 28.1 and 38.8 nm, which is in the middle of the results in Morawska et al. (2009).

Sort by PN concentration from low to high, black plain texts (A), texts and pictures in color (B), pictures in red (D), and pictures in multi-color (C) is the order, which is the same as the order of toner coverage, i.e., 5%, 10%, 20%, and 40%, respectively. He et al. (2007) and Wang et al. (2012) indicated that the particle emission positively correlates with toner coverage, while, in contrast, Schripp et al. (2008) and Morawska et al. (2009) found little effect of toner coverage on the particle emission. Note that although SMPS shows that both the highest PN and GSA concentrations from D are 1.5 times higher than B, WS shows no significant difference. This disagreement between SMPS and WS is attributed to the overestimation from the SMPS scan due to the rapid change of aerosol concentration, which was observed by WS.

The same thing about C and D is that they all printed only pictures. However, the GSA concentration from C, which is the highest among all prints, is about 3 times higher than D. Except the higher toner coverage (40%), the multi-color printing could be another reason for the higher concentration compared with monochrome printing in D. Our results are consistent with previous studies (Schripp et al., 2008; He et al., 2010), where He et al. (2010) showed that multi-color printing leads to 2–3 times more PN concentration than monochrome printing for the same printer, although the reason remains unclear. Many other parameters are also affecting the PN concentration including the printing speed, toner temperature, and toner cartridge condition (Pirela et al., 2017). However, other than monochrome and color printing, the parameters affecting the PN concentration are beyond the scope of this study and unable to be identified from this data set since the field measurements were not strictly controlled for comparison.

**3D Printing**

The 3-h time series of the GSA and PN concentrations were shown in Figs. 7(a) and 7(b), respectively, where the solid line represents WS and the dotted line represents SMPS. The timeline was also indicated in the figure. The printer was turned on at Min 26 and started warming up with the internal ventilation on. The 1ˢᵗ and the 2ˢᵗ prints started at Min 48 and 128, respectively. Each print took 70 min. The sampling tube was outside the enclosure from the beginning until Min 128 and moved into the enclosure.

It is apparent that the concentration inside the enclosure was much higher than that outside the enclosure, e.g., the GSA concentration inside at the very beginning of the 2ⁿᵈ print was about two orders of magnitude higher than that outside. An obvious PN peak (Min 30–45; Fig. 7(b)) was detected right after the printer was turned on and the concentration stayed elevated for at least 10 min. We feel that the emission was not leaking from the enclosure since no obvious peak was found during the 1ˢᵗ print, whose PN concentration in the chamber should be as high as 1 × 10⁶ # cm⁻³, similar to the 2ⁿᵈ print. Thus, the peak right after the boot of the 3D printer was most likely due to other random events happened in the room.

For the 2ⁿᵈ print, the GSA concentration rose quickly to 5 × 10⁴ μm² cm⁻³. The reason for the high emission is that preheating the materials generates large amounts of particles...
Fig. 6. (a) Time series of the GSA concentration and (b) exemplary aerosol size distributions for the prints of A, B, C, D, and the background.
(Azimi et al., 2016; Zhang et al., 2018). What makes the measurements challenging is the wave pattern with 16 waves in the 70-min printing (Fig. 7). In addition, the peak is more than an order of magnitude higher than the valley in several waves. The pattern was most likely due to the combination of the constant particle generation and the efficient air filtration of 4 fan filters. Fig. 7(c) shows the PN concentration-diameter distribution over time from the start of the 2nd print.
to the end of the sampling. In spite of the wavy concentration, both methods agreed extremely well with each other during the measurement with a Pearson correlation coefficient of 0.88 from the linear comparison in Fig. 5.

The peak PN concentrations of the waves for printing with ABS filaments were between $1 \times 10^6$ to $1 \times 10^9$ # cm$^{-3}$. This particle emission range was consistent with other studies that have also measured the ABS emission of 3D printing (Stephen et al., 2013; Azimi et al., 2016; Zhang et al., 2017; Zhang et al., 2018). Stephens et al. (2013) reported on measurements of 3D printer emission inside a commercial office space, where the highest concentration is $1.5 \times 10^9$ # cm$^{-3}$ when 2 printers with PLA and 3 printers with ABS were on at the same time. Azimi et al. (2016) measured the emission from ABS printing in a 3.6-m$^3$ chamber with a mixing fan with the PN concentration from $4 \times 10^5$ to $1 \times 10^9$ # cm$^{-3}$ for the main printing. Zhang et al. (2017) monitored 6 printers with various materials in a 1-m$^3$ environmental chamber with 1 air change per h. The average maximum concentration for ABS printing is between $1 \times 10^8$ and $1 \times 10^9$ # cm$^{-3}$. The geometric mean diameter and the geometric standard deviation of the distribution ($\sigma_g$) in Fig. 7(c) were 67.0 $\pm$ 25.4 and 2.0 $\pm$ 0.3, respectively. The CMD (= GMD) for the ABS measurement in Kim et al. (2015) is 32.6 $\pm$ 1.1 during printing and 50.5 $\pm$ 1.1 after the operation. The peak diameter was between 36.5 and 48.7 nm in Stephens et al. (2013). The average GMD is around 65 nm for the ABS printing in Zhang et al. (2017). Note that the GMD for 3D printing was about twice that from laser printing (28.1–38.8 nm) in our measurements.

The three factors including the internal air circulation, the filtration system, and the well-sealed printing chamber make our measurement different from other measurements of 3D printer emission. We observed a drastic concentration drop within a few minutes of printing stop, while it took more than half an hour for the concentration to drop to the background level in the above studies. This indicates that an internal filtration system with an enclosure (not necessarily airtight) could be one of the solutions to the emission problem of the 3D printers. In fact, the model results in Zhang et al. (2018) suggested removing particles near the extruder nozzle to eliminate 3D printing emission.

Machining

The emissions of multiple events in the machine shop were measured and the 4.5-h time series of the GSA concentrations were shown in Fig. 8. The particle concentration of the waterjet cutting was as low as the background during the warming up; the main cutting lasted 5 min and the concentration stayed elevated at 700 μm$^2$ cm$^{-3}$. Although the background concentration for the sanding was slightly lower than that of waterjet cutting, once the grinding began, the concentration rose to the level of waterjet cutting. In the middle of the grinding process, the local exhaust ventilation was turned on and the emission was immediately eliminated.

Therefore, the LEV is a very effective option to protect the workers against the particle emission. The emission from the welding process was extremely high compared with other machining processes. For example, the highest concentration from welding (even with LEV) was one magnitude higher than those from the waterjet cutting and sanding and slightly lower than the first burst in 3D printing (Section 3.2). Thus, the LEV must be turned on all the time to protect the worker against the severe emission. However, the efficient particle removal of the LEV and the burst of particle generation led to the drastic change in the emission in a wide concentration range in seconds, namely, very transient and unstable that made the measurement extremely difficult. As a result, welding had much larger errors for the WS method compared with waterjet cutting and sanding; SMPS frequently obtained inaccurate scans that may not represent the true aerosol distribution.

In general, the WS and SMPS methods agreed well with each other with Pearson correlation coefficients of 0.87, 0.67, and 0.89 for waterjet cutting, welding, and sanding, respectively. Although the emission from welding was fairly transient, the concentrations and trends from both methods were still comparable.

Ambient Environment

The outdoor GSA concentration was monitored for about 6 h from 10:00 to 16:00 (Fig. 9). The concentration was

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**Fig. 8.** Time series of GSA concentrations in the machine shop by SMPS and WS.
between 200 and 500 μm² cm⁻³, which is consistent with the 5-d outdoor GSA measurement in Cao and Pui (2018). Although SMPS shows more fluctuation than WS that was already explained in Section 4.4 in Cao and Pui (2018), the results from both methods agreed with each other for the duration with a Pearson correlation coefficient of 0.94. The PN concentration is shown in Fig. 9(b) along with the 24-h data from Cao and Pui (2018).

The range of PN concentration in this study is between 2,440 and 15,500 # cm⁻³, which is consistent with the results in Cao and Pui (2018), between 3,660 and 27,200 # cm⁻³.

CONCLUSION

This study investigated the accuracy of the weighted-sum approach, which was developed to measure the aerosol geometric surface area concentration in real time (Cao and Pui, 2018), for various scenarios. To that end, we applied the WS method and concurrently used an SMPS to measure the particle GSA concentrations emitted during laser printing, 3D printing, and machining, as well as those present in the ambient environment. The two methods agreed well with each other across a wide range of concentrations, with an overall Pearson correlation coefficient of 0.85, despite large uncertainties for the extremely transient aerosol produced by welding. Fortunately, Su et al. (2019a) demonstrated a solution to this obstacle by setting a maximum time resolution of 1 s. Using the GSA concentrations measured in this study as a reference, affected personnel can protect themselves accordingly. Additional systematic measurements can be conducted in future research to assess the relationship between GSA concentrations and adverse health effects.

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