

New Gaussian Plume Equation for the Impacts of Dust Storms on Radionuclide Transport

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ABSTRACT

Potential impacts of dust storms on radionuclide atmospheric dispersion have been the focus of great attention lately by countries that opted to build nuclear power plants in arid regions. The Gaussian point source dispersion equations have been modified to incorporate the rate of scavenging of gaseous radioactive plumes emitted from nuclear power plants due to adsorption by nanoaerosols that come from dust storms. The radionuclide-nanoaerosol interaction has been built based on the flux-matching theory assumptions: the size of a particle has the same order of magnitude of the mean free path of the molecules of air, and the adsorption coefficient is time-dependent. A correction factor (λ_r) has been introduced to the Gaussian plume equation to represent the fraction of the remaining radionuclides in the atmosphere at any distance downwind. A case study involving iodine-131 was used to apply the modified equations and to estimate the correction factor for different dust storms. The fraction of the adsorbed radionuclides on the atmospheric nanoaerosols ($1 - \lambda_r$) varies from less than 0.1 during a dust storm that has a density of 10 µg m⁻³ to more than 0.9 during a heavy dust storm of 1000 µg m⁻³ of density. Therefore, 90 percent of the transported radionuclide plume can be adsorbed by the atmospheric nanoaerosols in normal days. These findings pose new challenges since radionuclides can be carried by nanoaerosols to farther distances than what is normally expected.

Keywords: Nanoaerosols; Dust storms; Radionuclides; Gaussian dispersion.

INTRODUCTION

Atmospheric nuclear emissions (radionuclides) from nuclear power plants are one of the most dangerous emissions to the environment (EPA, 2000). They can harm humans, animals, plants and all environmental components within several kilometers from their source. These emissions along with those from other power plants or industrial activities disperse in plumes into the atmosphere and have been commonly modelled by the atmospheric diffusion-dispersion equation that is represented by the Gaussian plume equation (GPE) (Masters and Ela, 2007). Radionuclide transport in the atmosphere depends mainly on several parameters and conditions, most of which greatly depend on the climate of the region of interest, such as atmospheric stability and wind speed. However, many other conditions can affect radionuclide plume transport, such as the amount of effluent released into the atmosphere, the removal mechanisms of the released effluent, the height of the release, the momentum and buoyancy of the emitted plume, the geographic features and some other

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conditions (NRC, 1977).

Areas that are affected by unusual weather conditions such as sand and/or dust storms cover the region of interest with huge amounts of dust for a long period of time. Under such conditions, the behavior of the emitted radionuclides and the potential effects on the emission plumes have not been studied as revealed by a literature review on the subject (Engelstaedter *et al.*, 2006; Abed *et al.*, 2009; Athanasopoulou *et al.*, 2016), meaning that there is a real need to understand and model such impacts. Countries (including Egypt, United Arab Emirates and Jordan) that are affected by Khamaseen storms and opted to build nuclear power plants (Ganor *et al.*, 1981; Alpert and Ganor, 2001; Shahsavani *et al.*, 2012; Krasnov *et al.*, 2013; Alghamdi *et al.*, 2015; Saraga *et al.*, 2017; Jaafari *et al.*, 2017) have a greater need and concern.

The existence of the dust in the atmosphere is different from one region to another and depends on several conditions such as location, rate of precipitation, and the general meteorology of the region during the year. Jordan, like most of the countries in the Middle East, is exposed annually to several dust storms that come from the Sahara of North Africa (Abed *et al.*, 2009). These dust storms (locally known as Khamaseen cyclones) reform frequently in a limited period of spring each year and can travel thousands of kilometers from the North African Sahara to reach the Eastern Mediterranean region carrying a huge amount of

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dust and aerosols that makes a significant change in the environmental stability and changes in the climate of the countries through which they pass.

The Khamaseen cyclones, with their heavy load of nanoaerosols, can make an effect on the transported radionuclide concentration emitted from the nuclear plants due to the potential sorption of these radionuclides onto the large surface area of the nanoaerosols, making them spread in a long distance. However, such effects have not been studied yet simply because the Khamaseen cyclones and these types of extreme events are not widespread around the world, especially the countries that use nuclear power plants. Nevertheless, impacts of dust storms on the building in regions subjected to these storms have been investigated by Doronzo *et al.* (2014, 2015). In summary, the potential impacts of the dust on the emitted radionuclides and their transportation in the atmosphere are not well understood and need further exploration.

In this study, the commonly used Gaussian point source equations have been modified to incorporate the potential interaction between the emitted radionuclides and the nanoaerosols from dust storms. Results are compared with the available experiment of Noguchi *et al.* (1990) on adsorption of the gaseous iodine-131 on atmospheric nanoaerosols.

MODEL DEVELOPMENT

When radionuclides or any other emitted pollutants are applied to the porous medium of the aerosols in the atmosphere, these radionuclides do not act as a conservative tracer, due to the electrical charge difference between the aerosols, which have a negative charge, and the radionuclides, which may make a strong bond on the huge surface area of the aerosols due to the adsorption phenomenon (Tindall, 1999). The general diffusion-dispersion equation with a reaction term represents the rate of scavenging of radionuclides due to adsorption by atmospheric nanoparticles as shown in Eq. (1).

$$\frac{\partial C}{\partial t} + \overline{u} \frac{\partial C}{\partial t} = K_{xx} \frac{\partial^2 C}{\partial x^2} + K_{yy} \frac{\partial^2 C}{\partial y^2} + K_{zz} \frac{\partial^2 C}{\partial z^2} + R(c,t)$$
(1)

where C is the concentration of diffused molecules (radionuclides), t is the time, \overline{u} is the average wind speed, K_{xx} , K_{yy} and K_{zz} are the diffusivity constants for the diffused molecules in the three dimensions, and the last term represents the reaction term as a function of concentration and time.

In this study, the reaction term was represented by the flux-matching theory approach. This theory was suggested by Fuchs *et al.* (1964), Loyalka *et al.* (1983), Lushnikov *et al.* (2004) and Hales *et al.* (2002) and developed by Elperin *et al.* (2017) to estimate the scavenging coefficient (the adsorption coefficient) as a function of time. This coefficient represents the rate of adsorption of gaseous radionuclides (pollutants) emitted from smoke stacks in industrial activities on atmospheric nanoaerosols. The following assumptions are the main assumptions made for determining the adsorption coefficient based on flux-matching theory:

(1) The size of nanoaerosols has the same order of magnitude as the mean free path of air molecules (lies in the transition regime; Knudsen number $K_n = 1$) (Seinfeld and Pandis, 2006). (2) Aerosol particles are uniformly distributed in the plume area. (3) Aerosol particles and trace gas molecules have the same velocity, which is equal to the wind speed. (4) Pollutants are in the gaseous phase. Following a similar approach to that suggested by Elperin *et al.* (2013) and Elperin *et al.* (2018), the reaction term of the general diffusion-dispersion equation is represented by Eq. (2).

$$\frac{\partial C_G}{\partial t} = \left(\gamma + \frac{m\varphi_s \tau_D^{-1} \exp\left(-\frac{1+m\varphi_s}{\tau_D}\right)t}{1-\frac{1+m\varphi_s}{m\varphi_s} \left(1-\exp\left(-\frac{1+m\varphi_s}{\tau_D}t\right)\right)} \right) - C_G \qquad (2)$$
$$= -\lambda(t)c$$

where *c* is the concentration of gaseous radionuclides ($g m^{-3}$), $\lambda(t)$ is the scavenging coefficient (s⁻¹), γ is the radioactive decay constant (s⁻¹), m is the adsorption coefficient (given by $m = K'S_{sp}$; which is dimensionless and depends on the linear adsorption coefficient of radionuclides on atmospheric nanoaerosols K' (cm), and the specific surface area of the aerosols S_{sp} (m² cm⁻³)), τ_D is the characteristic time of mass transfer (s) (given by $\tau_D = am/3K_G$; depends on the radius of the aerosol particle a (m), the dimensionless adsorption coefficient *m*, and the coefficient of mass transfer K_G (m s⁻¹)), and φ_s represents the volume fraction of the aerosol particles in the atmosphere (given by $\varphi_s = n(4/3)\pi a^3 = \rho_D/\rho_s$ where n is the number concentration of aerosols, ρ_D is the mass concentration of aerosols per unit volume of air (µg m⁻³), and ρ_s is the density of aerosols (µg m⁻³)). Substitution of Eq. (2) in the reaction term of Eq. (1) is shown in Eq. (3).

$$\frac{\partial C}{\partial t} + \overline{u} \frac{\partial C}{\partial x} = K_{xx} \frac{\partial^2 C}{\partial x^2} + K_{yy} \frac{\partial^2 C}{\partial y^2} + K_{zz} \frac{\partial^2 C}{\partial z^2} - \lambda(t)c \qquad (3)$$

To simplify the term that represents the scavenging coefficient, the following assumptions are applied: $l = m\varphi_s/\tau_D$, $b = (m\varphi_s + 1)/\tau_D$, $s = m\varphi_s/(m\varphi_s + 1)$, and d = 1 - s. Substitution of *l*, *b*, *s* and *d* in Eq. (3) is shown in Eq. (4).

$$\frac{\partial C}{\partial t} + \overline{u} \frac{\partial C}{\partial x} = K_{xx} \frac{\partial^2 C}{\partial x^2} + K_{yy} \frac{\partial^2 C}{\partial y^2} + K_{zz} \frac{\partial^2 C}{\partial z^2} - \left(\gamma + \frac{a}{de^{bt} + s}\right)c$$
(4)

This equation has been solved subject to initial and boundary conditions of $C(x, y, z, 0) = S \,\delta(x)\delta(y)\delta(z)$ and C(x, y, z, t) = 0 when $x, y, z \to \overline{+} \infty$, respectively, where S represents the source strength from instantaneous point source and $\delta(x)$, $\delta(y)$ and $\delta(z)$ the Dirac-delta function in the three dimensions. Applying separation-of-variables technique, the concentration is divided into three components in the x, *y* and *z* directions as shown in Eq. (4). Initial conditions of the three components are $C(x, 0) = S^{1/3}\delta(x)$, $C(y, 0) = S^{1/3}\delta(y)$, and $C(z, 0) = S^{1/3}\delta(z)$.

$$C(x, y, z, t) = C_x(x, t)C_y(y, t)C_z(z, t)$$
(5)

Based on the assumption in Eq. (5), Eq. (4) is reduced to the following:

$$\frac{\partial C_x}{\partial t} + \overline{u} \frac{\partial C_x}{\partial x} = K_{xx} \frac{\partial^2 C}{\partial x^2} - \left(\gamma + \frac{l}{de^{bt} + s}\right)C$$
(6)

$$\frac{\partial C_{y}}{\partial t} = K_{yy} \frac{\partial^{2} C_{y}}{\partial y^{2}}$$
(7)

$$\frac{\partial C_z}{\partial t} = K_{zz} \frac{\partial^2 C_z}{\partial z^2} \tag{8}$$

Each of Eqs. (6)–(8) can be solved independently by using Fourier transform to form the full solution of the GPE. The reaction term is assumed to be in the *x* direction only because the plume spread in the *x* direction is much higher than that in the other directions. To begin the solution of Eq. (6) (in the *x* direction), Fourier transform is applied on each term of Eq. (6), which gives

$$\frac{\partial C}{C(\alpha,t)} = -\left[i\alpha \ \overline{u} + K_{xx}\alpha^2\right] + \left(\gamma + \frac{l}{de^{bt} + s}\right)\partial t \tag{9}$$

Taking the integration of the two sides of Eq. (9) gives

$$C(\alpha,t) = C_1(\alpha,t) \exp\left[-\left(i\alpha \ \overline{u} + K_{xx}\alpha^2 + \gamma\right)t\right] \left(\frac{de^{bt} + s}{e^{bt}}\right)$$
(10)

The integration constant $C_1(\alpha, t)$ refers to the initial concentration (at t = 0), which is $C_1(\alpha, 0)$, and can be obtained by applying Fourier transform on the initial condition, giving $C(x, 0) = S^{1/3}\delta(x)$ and $C_1(\alpha, 0) = S^{1/3}/(2\pi)^{1/2}$ where S is the source strength from instantaneous point source. Substitution of the constant of the integration in Eq. (10) gives

$$C(\alpha,t) = \frac{S^{1/3}}{(2\pi)} \exp\left[-\left(i\alpha \ \overline{u} + K_{xx}\alpha^2 + \gamma\right)t\right] \left(\frac{de^{bt} + s}{e^{bt}}\right) (11)$$

By applying the inverse Fourier transform on Eq. (11), C(x, t) becomes as follows:

$$C(x,t) = \frac{1}{\left(2\pi\right)^{1/2}} \int_{-\infty}^{\infty} \frac{S^{1/3}}{\left(2\pi\right)^{1/2}} e\left[-\left(i\alpha \ \overline{u} + K_{xx}\alpha^{2} + \gamma\right)t\right] e^{i\alpha x} \left(\frac{de^{bt} + s}{e^{bt}}\right) d\alpha$$
(12)

This equation is an integration with respect to the variable α . Using completing-the-square technique, it can be simplified to give the following:

$$C(x,t) = \frac{S^{1/3}e^{-\gamma t}}{2\pi} \left(\frac{de^{bt} + s}{e^{bt}}\right) \int_{-\infty}^{\infty} e^{-\left(\alpha(K_{xx}t)^{1/2} - \frac{i(x-\bar{u}t)}{2(K_{xx}t)^{1/2}}\right)^2 - \frac{(x-\bar{u}t)^2}{4K_{xx}t}} d\alpha$$
(13)

To solve this equation, it is assumed that $\omega = \alpha (K_{xx}t)^{1/2} - i(x - u\bar{t})/[2(K_{xx}t)^{1/2}]$, and thus Eq. (13) gives

$$C(x,t) = \frac{S^{1/3} e^{-\gamma t}}{2\pi (K_{xx}t)^{1/2}} e^{-\frac{(x-\bar{u}t)^2}{4K_{xx}t}} \left(\frac{de^{bt}+s}{e^{bt}}\right) \int_{-\infty}^{\infty} e^{-\omega^2} d\omega \qquad (14)$$

Knowing that $\int_{-\infty}^{\infty} e^{-\omega^2} d\omega = \sqrt{\pi}$ and $\left(\frac{de^{bt} + s}{e^{bt}}\right) = (d + se^{-bt})$, Eq. (14) gives

$$C(x,t) = \frac{S^{1/3}}{\sqrt{2\pi} \left(2K_{xx}t\right)^{1/2}} \exp\left(-\frac{\left(x-\overline{u}t\right)^2}{4K_{xx}t} - \gamma t\right) \left(d + se^{-bt}\right)$$
(15)

This is the solution of the general diffusion-dispersion equation in the x direction. To complete the solution, Eqs. (7) and (8), have been solved in the same way, resulting in Eqs. (16) and (17).

$$C(y,t) = \frac{S^{1/3}}{\sqrt{2\pi} \left(2K_{yy}t\right)^{1/2}} \exp\left(-\frac{y^2}{4K_{yy}t}\right)$$
(16)

$$C(z,t) = \frac{S^{1/3}}{\sqrt{2\pi} \left(2K_{zz}t\right)^{1/2}} \exp\left(-\frac{z^2}{4K_{zz}t}\right)$$
(17)

The terms that include the diffusivity constants can be represented by the standard deviation and variance in the three dimensions (Seinfeld and Pandis, 1998) as $\sigma_x^2 = 2K_{xx}t$, $\sigma_y^2 = 2K_{yy}t$ and $\sigma_z^2 = 2K_{zz}t$. The standard deviation in the three dimensions can be determined using Pasquill-Gifford curves (Pasquill, 1961) or the practical equations of Martin *et al.* (1976) as functions of both the distance downwind and the atmospheric stability classes of Turner *et al.* (1970). Consequently, the full solution of the general diffusion-dispersion equation based on Eq. (5) is given by Eq. (18).

$$C(x, y, z, t) = \frac{S(de^{-\gamma t} + se^{-(b+\gamma)t})}{(2\pi)^{2/3}\sigma_x\sigma_y\sigma_z} \exp\left(-\frac{(x-\overline{u}t)^2}{2\sigma_x^2} - \frac{y^2}{2\sigma_y^2} - \frac{z^2}{2\sigma_z^2}\right)$$
(18)

This formula represents the concentration of the diffused particles for an instantaneous point source (S) at any point

downwind. However, the GPEs for a continuous point source (q) have been estimated based on the Lagrangian approach, taking the time integration of the concentration for the instantaneous point source from 0 to ∞ , as shown in Eq. (19).

$$C(x, y, z) = \lim_{t \to \infty} C(x, y, z, t)$$

= $\lim_{t \to \infty} \int_{0}^{t} Q(x, y, t \mid 0, 0, t') Q(z, t \mid H, t') q (de^{-\gamma t} + se^{-(b+\gamma)t}) dt'$
(19)

where Q(x, y, t | 0, 0, t') is the transition probability in the x and y directions, and Q(z, t | H, t') is the transition probability in the z direction as a function of the smoke stack height H in case of total reflection of the diffused material on the ground surface (Seinfeld and Pandis, 2006). These two functions are elaborated in Eqs. (20) and (21),

$$Q(x, y, t \mid 0, 0, t') = \frac{1}{2\pi \sigma_x \sigma_y} \exp\left(-\frac{\left(x - \overline{u}t\right)^2}{2\sigma_x^2} - \frac{y^2}{2\sigma_y^2}\right)$$
(20)

$$Q(z,t | H,t') = \frac{1}{(2\pi)^{1/2} \sigma_z} \left[\exp\left(-\frac{(z-H)^2}{2\sigma_z^2}\right) - \exp\left(-\frac{(z+H)^2}{2\sigma_z^2}\right) \right]$$
(21)

To evaluate the steady state concentration from a continuous point source, Eqs. (20) and (21) are substituted in Eq. (19) giving Eq. (22).

$$C(x, y, z) = \int_{0}^{\infty} \frac{q\left(de^{-\gamma t} + se^{-(b+\gamma)t}\right)}{(2\pi)^{3/2}\sigma_{x}\sigma_{y}\sigma_{z}} \exp\left(-\frac{\left(x - \overline{u}t\right)^{2}}{2\sigma_{x}^{2}}\right) - \frac{y^{2}}{2\sigma_{y}^{2}}$$
(22)
$$\times \left[\exp\left(-\frac{\left(z - H\right)^{2}}{2\sigma_{z}^{2}}\right) + \exp\left(-\frac{\left(z + H\right)^{2}}{2\sigma_{z}^{2}}\right)\right] dt$$

To evaluate the integration in Eq. (22), let

$$C(x, y, z) = C_1(x, y, z) + C_2(x, y, z) + C_3(x, y, z) + C_4(x, y, z)$$
(23)

where

$$C_{1}(x, y, z) = \int_{0}^{\infty} \frac{qs e^{-(b+y)t}}{(2\pi)^{3/2} \sigma_{x} \sigma_{y} \sigma_{z}} \exp\left(-\frac{(x-\overline{u}t)^{2}}{2\sigma_{x}^{2}} - \frac{y^{2}}{2\sigma_{y}^{2}} - \frac{(z-H)^{2}}{2\sigma_{z}^{2}}\right)$$
(24)

$$C_{2}(x, y, z) = \int_{0}^{\infty} \frac{qse^{-(b+\gamma)t}}{(2\pi)^{3/2} \sigma_{x} \sigma_{y} \sigma_{z}} \exp\left(-\frac{(x-\overline{u}t)^{2}}{2\sigma_{x}^{2}} - \frac{y^{2}}{2\sigma_{y}^{2}} - \frac{(z+H)^{2}}{2\sigma_{z}^{2}}\right)$$
(25)

$$= \int_{0}^{\infty} \frac{q d e^{-(b+\gamma)t}}{(2\pi)^{3/2} \sigma_x \sigma_y \sigma_z} \exp\left(-\frac{(x-\overline{u}t)^2}{2\sigma_x^2} - \frac{y^2}{2\sigma_y^2} - \frac{(z-H)^2}{2\sigma_z^2}\right)$$
(26)

and

 $C(\mathbf{x},\mathbf{y},\mathbf{z})$

$$C_{4}(x, y, z) = \int_{0}^{\infty} \frac{q d e^{-(b+y)t}}{(2\pi)^{3/2} \sigma_{x} \sigma_{y} \sigma_{z}} \exp\left(-\frac{(x-\overline{u}t)^{2}}{2\sigma_{x}^{2}} - \frac{y^{2}}{2\sigma_{y}^{2}} - \frac{(z+H)^{2}}{2\sigma_{z}^{2}}\right)$$
(27)

Each of the Eqs. (24)–(27) have been solved to get the full solution. Beginning with Eq. (23), the terms that represent the variances in the three dimensions depend on time. Therefore, the following assumptions were made: $a_x = 2K_{xx}$, $a_y = 2K_{yy}$, and $a_z = 2K_{zz}$. Then, Eq. (24) gives

$$C_{1}(x, y, z) = \frac{q s}{(2\pi)^{3/2} (\sigma_{x} \sigma_{y} \sigma_{z})^{1/2}} \int_{0}^{\infty} (t)^{-3/2} \exp\left(-\frac{(x - \overline{u}t)^{2}}{2\sigma_{x}t} - \frac{y^{2}}{2\sigma_{y}t} - \frac{(z - H)^{2}}{2\sigma_{z}t} - (b + \gamma)t\right) dt$$
(28)

Rearrangement of Eq. (28) yields

$$C_{1}(x, y, z) = \frac{qs}{(2\pi)^{3/2} (\sigma_{x} \sigma_{y} \sigma_{z})^{1/2}}$$

$$\int_{0}^{\infty} (t)^{-3/2} \exp \left[-\left[\frac{\left(x^{2} + \left(\frac{\sigma_{x}}{\sigma_{y}} \right) y^{2} + \left(\frac{\sigma_{x}}{\sigma_{z}} \right) (z - H)^{2} \right)}{2\sigma_{x} t} - \frac{2\overline{u}xt}{2\sigma_{x} t} + \frac{\overline{u}^{2} t^{2}}{2\sigma_{x} t} + (b + \gamma) t \right) \right] dt$$

$$(29)$$

Assuming $\beta^2 = x^2 + (a_x/a_y)y^2 + (a_x/a_z)(z - H)^2$ and $\omega = (t)^{-1/2}$, Eq. (29) becomes

$$C_{1}(x, y, z) = \frac{2 q s e^{\overline{u} x/a_{x}}}{\left(2\pi\right)^{3/2} \left(\sigma_{x} \sigma_{y} \sigma_{z}\right)^{1/2}} \int_{0}^{\infty} \exp\left[-\left(\frac{\beta^{2} \omega^{2}}{2 a_{x}} + \frac{2 a_{x} \left(b + \gamma\right) + \overline{u}^{2}}{2 a_{x} \omega^{2}}\right)\right] d\omega$$
(30)

This equation can be solved by using the following general form:

$$\int_{0}^{\infty} \exp\left[-\left(a\omega^{2} + \frac{b}{\omega^{2}}\right)\right] d\omega = \frac{1}{2} \left(\frac{\pi}{a}\right)^{1/2} e^{-2(ab)^{1/2}}$$
(31)

Substitution in Eq. (29) gives

$$C_{1}(x, y, z) = \frac{qs e^{\overline{u}x/a_{x}}}{2\pi \left(a_{y}a_{z}\right)^{1/2}\beta} \exp\left[-\frac{1}{a_{x}} + \left(\beta^{2}\overline{u}^{2} + 2a_{x}\beta^{2}\left(b+\gamma\right)\right)^{1/2}\right]$$

$$(32)$$

Using the approximation in Eq. (33) gives Eq. (34).

$$(x+y)^{1/2} \cong x^{1/2} + \frac{1}{2}x^{-1/2}y$$
(33)

$$\left(\beta^{2}\overline{u}^{2}+2a_{x}\beta^{2}\left(b+\gamma\right)\right)^{1/2}=\beta\overline{u}+\frac{a_{x}\beta\left(b+\gamma\right)}{\overline{u}}$$
(34)

Eq. (34) is substituted in Eq. (32) giving the following formula:

$$C_{1}(x, y, z) = \frac{qs}{2\pi (a_{y}a_{z})^{1/2} \beta}$$

$$\exp\left[-\left(\frac{\overline{u}}{a_{x}}(\beta - x)\right)\right] \exp\left[-\left((b + \gamma)\frac{\beta}{\overline{u}}\right)\right]$$
(35)

where

$$\beta = x(1 + ((a_x/a_y)y^2 + (a_x/a_z)(z - H)^2)/x^2)^{1/2} = x + x ((a_x/a_y)y^2 + (a_x/a_z)(z - H)^2)/[2x^2]$$
(36)

Therefore,

$$\beta - x = \frac{\left(\frac{a_x}{a_y}\right)y^2 + \left(\frac{a_x}{a_z}\right)\left(z - H\right)^2}{2x}$$

Knowing that u = x/t and that the applied distance in the x direction is much higher than that in the other two directions (i.e., $x \gg (a_x/a_y)y^2 + (a_x/a_z)(z - H)^2$), it can be approximated that $\beta \cong x = u\overline{t}$. Substitution of Eq. (36) in Eq. (35) gives

$$C_{1}(x, y, z) = \frac{qs}{2\pi\overline{u}(a_{y}t)^{1/2}(a_{z}t)^{1/2}}$$

$$\exp\left[-\left(\frac{y^{2}}{2a_{y}t} + \frac{(z-H)^{2}}{2a_{z}t}\right)\right]\exp\left[-\left((b+\gamma)\frac{x}{\overline{u}}\right)\right]$$
(37)

Eqs. (25)–(27) can be solved using the same method. Substituting the values of s, b and d in Eq. (23) gives the full solution of the modified Gaussian plume equation as follows:

$$C(x, y, z) = \frac{q \lambda_y e^{-y \frac{\lambda}{u}}}{2\pi \overline{u} \sigma_y \sigma_z} \exp\left(-\frac{y^2}{2\sigma_y^2}\right)$$

$$\left[\exp\left(-\frac{(z-H)^2}{2\sigma_z^2}\right) + \exp\left(-\frac{(z+H)^2}{2\sigma_z^2}\right)\right]$$
(38)

where $\lambda_r = [1 + m\varphi_s \exp(-(x/u)(1 + m\varphi_s)/\tau_D)/[1 + m\varphi_s]$. The correction factor λ_r represents the fraction of the radionuclides that remains in the atmosphere at any distance downwind the smoke stack. It depends mainly on the volume fraction of the aerosols in the atmosphere φ_s , the dimensionless coefficient of adsorption *m*, the average wind speed u, the distance downwind x, and the characteristic time of the mass transfer τ_D . Consequently, the correction factor λ_r at x = 0 (and t = 0) equals unity ($\lambda_{ro} = 1$), meaning that the radionuclide molecules have not yet transferred to the aerosol particles. For steady state conditions, the correction factor is given by $\lambda_{r,\infty} = 1/(1$ $+ m\varphi_s$, which is independent of time, and only depends on the dimensionless coefficient of adsorption and the volume fraction of aerosols in the atmosphere. In addition, the correction factor $(1 - \lambda_r)$ may be used to represent the fraction of radionuclides transferred to the aerosol particles.

RESULTS AND DISCUSSION

To represent the fraction of the transported radionuclides onto the atmospheric aerosols as a function of the distance downwind graphically using Eq. (38), iodine-131 was chosen as an example. Noguchi *et al.* (1990) studied the gaseous iodine adsorption by carbon-based ultrafine aerosols and estimated that the coefficient of diffusion D_G and the linear adsorption coefficient K' of the iodine are equal to 0.08 cm² s⁻¹ and 10⁴ m, respectively. Also, the specific surface area of the aerosol particles was assumed 100 m² cm⁻³, and the density of the ultrafine aerosol particles ρ_s was taken 1.2 g cm⁻³ according to Chen *et al.* (2010). Furthermore, the sticking probability S_p was assumed unity and the average wind speed 5 m s⁻¹.

The volume fraction of aerosol particles in the atmosphere φ_s during dust events depends mainly on the concentration of the aerosols. However, nanoaerosols are characterized by their abundance and their low weight in the air; these two properties can lead to transport nanoaerosols for long distances from their main source. The number of aerosols in the atmosphere during a dust storm depends mainly on the vegetarian cover and the wind speed in the region of interest (Kurosaki and Mikami, 2003). The dust storm classification depends mainly on the dust concentration in the atmosphere within the dust storm period and can be governed by PM_{2.5}, PM₁₀ or TSP (total suspended particles). Table 1 shows the mean values and peak values of aerosol concentrations for PM_{2.5}, PM₁₀ and TSP for many dust storms around the world

	Concentration of Aerosol	Location and Date of	Reference
	$(\mu g m^{-3})$	Occurrence	
Total Suspended Particles (TSP)	6000 (peak)	Northeast Asia (2000–2005)	Song <i>et al.</i> (2007)
	1021 (daily peak)	Palestine (1977)	Ganor <i>et al.</i> (1981)
Particulate Matter less than	9000 (peak)	Palestine (1998)	Alpert and Ganor (2001)
10 μm (PM ₁₀)	2568 (daily mean)	Palestine (2001–2012)	Krasnov et al. (2013)
	3986 (half hour peak)	Saudi Arabia (2012)	Alghamdi et al. (2015)
	1781 (peak)	Qatar (2015)	Saraga <i>et al.</i> (2017)
	1150 (daily mean)	Iran (2017)	Jaafari <i>et al</i> . (2017)
	5338 (peak)	Iran (2010)	Shahsavani et al. (2012)
	767 (daily peak)	China (2015)	Liu et al. (2014)
	5616 (peak)	Iran (2009)	Amanollahi et al. (2011)
	79600 (peak)	Cyprus (2015)	Mamouri et al. (2016)
Particulate Matter less than	700 (daily mean)	Palestine (2001–2012)	Krasnov et al. (2013)
2.5 μm (PM _{2.5})	868 (half hour peak)	Saudi Arabia (2012)	Alghamdi et al. (2015)
	1569 (peak)	Qatar (2015)	Saraga <i>et al.</i> (2017)
	55.8 (daily mean)	Iran (2017)	Jaafari <i>et al</i> . (2017)
	910 (peak)	Iran (2010)	Shahsavani et al. (2012)

Table 1. Concentration of aerosols (TSP, $PM_{2.5}$ and PM_{10}) in the atmosphere during dust storms from several studies around the world.

from several studies. Then by applying these assumptions in multiple dust storm events, the fraction of the adsorbed iodine into the atmospheric aerosols $(1 - \lambda_r)$ as a function of the distance downwind the stack can be represented by Fig. 1. These results show that the fraction of the adsorbed iodine onto the atmospheric aerosols $(1 - \lambda_r)$ is equal to zero at the origin of the smoke stack (at x = 0) and increases within a few meters downwind to reach the steady state value (the maximum value). Also, the dust events of high aerosol densities reach the steady state value faster than the dust events of low densities. Jaafari et al. (2017) estimated that PM₁/PM₁₀ during dust events can reach 0.23, meaning that 23 percent of PM_{10} has a size of particles less than 1 μm and thus is constituted as nanoparticles. Thus, the dust storm that has a PM_{10} concentration of 4000 µg m⁻³ may have a PM_1 concentration of 1000 µg m⁻³. Therefore, values of PM_1 that were used to estimate the factor $(1 - \lambda_r)$ in Fig. 1 ranged from 10 to 1000 $\mu g m^{-3}$.

This study assumes that Knudsen number is constant and has a value of 1 for all dust storm densities. The fraction of the adsorbed iodine-131 onto atmospheric aerosols for dust events that have a density of 1000 $\mu g~m^{-3}$ increased rapidly from zero to reach the steady state value of 0.9 within the first 10 meters downwind. This means that the aerosols can adsorb 90 percent of the emitted iodine-131 from the smoke stack at this level aerosols' density. On the other hand, the dust events that have an aerosols' density of 10 µg m⁻³ will increase slowly from zero to reach the maximum value of 0.07 at x = 50 m, meaning that it takes more time to reach the steady state and the adsorbed amount of iodine-131 on the atmospheric aerosols that is much lower than that for the denser dust events. Fig. 2 shows the relationship between the rate of adsorption of the radioactive gas into the atmospheric aerosols as a function of time for several values of sticking probability S_p at a specific value of aerosols' density ρ_s that equals 1000 μ g m⁻³. These results show that as the sticking probability decreases, the time required to reach the steady state value of $(1 - \lambda_r)$ also decreases. This is due to the fact that as the sticking probability value decreases, the number of effective collisions between the radioactive gas and the aerosol particles decreases, which leads to decreasing the time required to reach the steady state value. The theoretical results of this study make an agreement with the experimental results of Noguchi *et al.* (1988) and Noguchi *et al.* (1990). Their studies estimated the rate of adsorption of gaseous radioactive iodine-131 on atmospheric aerosol particles.

CONCLUSION

The Gaussian plume equations were modified in this study to include the potential impact of the atmospheric aerosols on the transported gaseous radionuclides from the nuclear power plant based on the flux-matching theory approaches by assuming that the adsorption coefficient of the gaseous radionuclides on the atmospheric nanoaerosols in the reaction term of the general diffusion-dispersion equation is time-dependent, and the size of the aerosol particles has the same order of magnitude of the mean free path of air molecules (transition regime; $Kn \cong 1$).

Several dust storms including the Khamaseen cyclones were characterized in this study from the literature; this characterization included the particle size distribution of several dust storms (TSP, PM_{2.5} and PM₁₀) as shown in Table 1 that which shows that the density of PM₁₀ in the atmosphere during dust events in Palestine (Khamaseen cyclones) had reached a peak and daily mean values of 9000 μ g m⁻³ (Alper and Ganor, 2001) and 2568 μ g m⁻³ (Krasnov *et al.*, 2013), respectively. Also, Saraga *et al.* (2017) estimated that the peak value of concentration of PM_{2.5} in the atmosphere during a dust event in Qatar in 2015 had reached 1569 μ g m⁻³. Krasnov *et al.* (2013) estimated that the daily mean value of



Fig. 1. Fraction of the adsorbed iodine-131 into the atmospheric aerosols $(1 - \lambda_r)$ as a function with the distance downwind of the stack for different values of mass concentrations of aerosols (ρ_D).



Fig. 2. Fraction of the radioactive iodine-131 into the atmospheric aerosols as a function with time for several values of sticking probability S_p at the aerosols' density of 1000 µg m⁻³.

concentration of PM_{2.5} in the atmosphere during dust events in Palestine from 2011 to 2012 had reached 700 µg m⁻³. Dust storms' concentrations used in the results of this study were taken to satisfy the limitation of $Kn \cong 1$.

This modification introduced the correction factor (λ_r) into the Gaussian plume equation which was applied to the fraction of the remaining gaseous radionuclides in the atmosphere at any point downwind as shown in Eq. (38). Also, this study indicates that the $(1 - \lambda_r)$ values range from less than 0.1 for dust events with small concentrations of nanoaerosols (PM₁ = 10 µg m⁻³) to more than 0.9 for the heavy dust storms (PM₁ = 1000 µg m⁻³) as shown in Fig. 1.

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